



# Single-Trial Adaptive Decoding of Concatenated Codes

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- Since their invention by Forney in 1966, serially concatenated codes are frequently used in applications.
- Reason: Easily decodable component codes might be chosen resulting in low overall decoding complexity.
- However, decoding up to half the minimum concatenated code distance is non-trivial. Multiple decoding trials are required.
- Several approaches to optimize single-trial decoding by [Zyablov, 1973], [Kovalev, 1986], (some refinements in [Weber and Abdel-Ghaffar, 2003]), [Sorger, 1993] and [Kötter, 1993].
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- All previous approaches assume outer BMD decoding we derive a single-trial algorithm for outer BD decoding!



Codeword of outer code  $\mathcal{C}^{\mathrm{o}}(\mathbb{F}_{p^m}; n^{\mathrm{o}}, k^{\mathrm{o}}, d^{\mathrm{o}})$ 

 $\mathbf{c}^{\mathrm{o}} \in \mathcal{C}^{\mathrm{o}}$ 



Codeword of outer code  $\mathcal{C}^{\mathrm{o}}(\mathbb{F}_{p^m}; n^{\mathrm{o}}, k^{\mathrm{o}}, d^{\mathrm{o}})$ 

Map symbols from  $\mathbb{F}_{p^m}$  to column vectors from  $\mathbb{F}_p^m$ 









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### **Classical Decoding of Concatenated Codes**



#### Received word $oldsymbol{R}=oldsymbol{C}+oldsymbol{E}$



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## **Decoding Radius of Classical Decoding**



Classical decoding as described above guarantees to decode

$$e < \frac{d^{\mathbf{o}}d^{\mathbf{i}}}{4}$$

channel errors [Forney, 1966].

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# Multi-Trial Error/Erasure Decoding of Conc. Codes



- Input for the outer decoder is  $\mathbf{r}^{o} = (r_{1}^{o}, \dots, r_{n^{o}}^{o}).$
- For each symbol r<sup>o</sup><sub>j</sub> inner decoding implicitly yields the unreliability measure Δ<sub>j</sub> := d<sub>H</sub>(**r**<sup>i</sup><sub>j</sub>, **č**<sup>i</sup><sub>j</sub>). W.I.o.g. Δ<sub>j</sub> ≥ Δ<sub>j+1</sub>.
- Decoding in  $d^{\circ}/2$  trials with increasing number of erased (X) most unreliable received symbols:



- Result: List of at most  $d^{\rm o}/2$  codeword candidates.
- Selection among the list possible by known criterion.

# Decoding Radius of Multi-Trial Decoding

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• Multi-trial error/erasure decoding as described above guarantees to decode

$$e < \frac{d^{\mathrm{o}}d^{\mathrm{i}}}{2}$$

channel errors.

• In literature, procedure is called Generalized Minimum Distance (GMD) decoding [Forney, 1966].

# Single-Trial Approaches

• [Zyablov, 1973] proposes single-trial decoding by fixing a static threshold T for erasing received symbols, i.e.  $r_j^{o}$  is erased if  $\Delta_j > T$ . The decoding radius is

$$e < \frac{d^{\mathbf{o}}d^{\mathbf{i}}}{3}.$$

Threshold T is chosen independently of  $\Delta$ .

• [Kovalev, 1986] takes the unreliabilities  $\Delta$  into consideration (adaptive decoding). Bounds for the decoding radius give

$$e < \rho \approx \frac{3d^{\mathrm{o}}d^{\mathrm{i}}}{8}.$$

• Aforementionend approaches assume outer BMD decoding. Our task: Derive an adaptive single-trial decoder assuming outer BD decoding!



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## Derivation of a Single-Trial Adaptive Decoder

• Assume an outer BD decoder with error/erasure tradeoff parameter  $1 < \lambda \leq 2$ . Outer decoding fails if

$$\lambda \varepsilon + \tau > d^{\rm o} - 1.$$

• For given number au of erasures (X), outer decoding fails if

$$\varepsilon(\tau) \geq \left\lfloor \frac{d^{\mathrm{o}} - \tau - 1}{\lambda} \right\rfloor + 1.$$

• For given unreliabilities  $\Delta := (\Delta_1, \dots, \Delta_{n^o})$ ,  $\Delta_j \ge \Delta_{j+1}$ , the minimum number of channel errors to obtain  $\varepsilon(\tau)$  errors is

$$e_{\tau}(\mathbf{\Delta}) := \sum_{j=1}^{\tau} \Delta_j + \sum_{j=\tau+1}^{\tau+\varepsilon(\tau)} (d^{\mathbf{i}} - \Delta_j) + \sum_{j=\tau+\varepsilon(\tau)+1}^{n^{\mathbf{o}}} \Delta_j$$
$$= \sum_{j=1}^{n^{\mathbf{o}}} \Delta_j + \sum_{j=\tau+1}^{\tau-\varepsilon(\tau)} (d^{\mathbf{i}} - 2\Delta_j).$$



# Single-Trial Outer Error/Erasure Decoding



- Input. Received vector  $\mathbf{r}^{o}$ , ordered unreliabilities  $\boldsymbol{\Delta}$  from inner decoder.  $d^{i}$ ,  $d^{o}$  and parameter  $1 < \lambda \leq 2$ .
- Step 1. Find  $\tau^* = \underset{\tau \in \{0,...,d^{\circ}-1\}}{\operatorname{arg\,max}} \sum_{j=\tau+1}^{\tau+\varepsilon(\tau)} (d^{i} 2\Delta_j).$
- Step 2. Decode  $\mathbf{r}^{o}$  with erased most unreliable (first)  $\tau^{*}$  positions by error/erasure decoder for  $C^{o}$  with error/erasure tradeoff parameter  $\lambda$ .
- Output. Either a codeword of  $C^{o}$  or decoding failure.

## Decoding Radius of Single-Trial Decoder



• General decoding radius of the single-trial decoder by assuming the "worst" unreliability vector  $\Delta$  and choosing the "best" number of erasures  $\tau$ , i.e.

$$\rho(\lambda) := \min_{\mathbf{\Delta}} \max_{\tau} e_{\tau}(\mathbf{\Delta}).$$

• Next step: Derive bounds on  $\rho(\lambda)!$ 

# Simplified Formula for the General Decoding Radius



- Transform *un*reliabilities  $\Delta$  into normalized reliabilities h by  $h_j := (d^i 2\Delta_j)/d^i$ . It holds:  $0 \le h_1 \le \cdots \le h_{n^\circ} \le 1$ .
- Decoding radius for fixed h and  $\tau$ :

$$e_{ au}(oldsymbol{h}) := d^{\mathrm{i}}\left(rac{1}{2}\sum_{j=1}^{n^{\mathrm{o}}}(1-h_j) + \sum_{j= au+1}^{ au+arepsilon( au)}h_j
ight).$$

• General decoding radius:

$$\rho(\lambda) = \min_{\boldsymbol{h}} \max_{\tau} e_{\tau}(\boldsymbol{h}).$$

• Observe that selection of  $\tau$  does not depend on  $h_{d^{o}+1}, \ldots, h_{n^{o}}$ . Simplification:

$$\rho(\lambda) = d^{\mathbf{i}} \left( \frac{d^{\mathbf{o}}}{2} - \max_{\mathbf{h}} \min_{\tau} \left( \frac{1}{2} \sum_{j=1}^{\mathbf{d}^{\mathbf{o}}} \mathbf{h}_{j} - \sum_{j=\tau+1}^{\tau+\varepsilon(\tau)} \mathbf{h}_{j} \right) \right)$$

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### Bounds for the Error Correcting Radius (1)

#### Theorem (Lower Bound)

$$\rho(\lambda) \geq \underline{\rho}(\lambda) := \frac{d^{\mathrm{i}}}{2} \left( \left\lfloor \frac{d^{\mathrm{o}} - 1}{\lambda} \right\rfloor + \left\lfloor \frac{d^{\mathrm{o}} - \left\lfloor \frac{d^{\mathrm{o}} - 1}{\lambda} \right\rfloor - 2}{\lambda} \right\rfloor + 2 \right)$$

Proof (Sketch): For any minimization we have

$$\min_{s \in \mathcal{S}} f(s) \le \min_{s \in \mathcal{S}' \subseteq \mathcal{S}} f(s) \le \frac{1}{|\mathcal{S}'|} \sum_{s \in \mathcal{S}'} f(s).$$

From this we get

$$\min_{\tau} \left( \frac{1}{2} \sum_{j=1}^{d^{\circ}} h_j - \sum_{j=\tau+1}^{\tau+\varepsilon(\tau)} h_j \right) \le \frac{1}{2} \sum_{j=\varepsilon(0)+\varepsilon(\varepsilon(0))+1}^{d^{\circ}} h_j.$$

## Bounds for the Error Correcting Radius (2)

Maximizing this term over h by setting all involved  $h_j$  to 1 gives

$$\max_{\boldsymbol{h}} \left( \frac{1}{2} \sum_{j=\varepsilon(0)+\varepsilon(\varepsilon(0))+1}^{d^{\mathrm{o}}} h_j \right) \leq \frac{1}{2} \left( d^{\mathrm{o}} - \varepsilon(0) - \varepsilon(\varepsilon(0)) \right).$$

Theorem (Upper Bound)

$$\rho(\lambda) \leq \overline{\rho}(\lambda) := \frac{d^{\mathrm{i}}}{\lambda} \left( d^{\mathrm{o}} - 1 - \frac{1}{2} \left\lfloor \frac{d^{\mathrm{o}} - 1}{\lambda} \right\rfloor \right)$$

# Decoding Radius Deduced from the Bounds



• From the bounds we can deduce the decoding radius

$$e < \rho(\lambda) \approx \frac{d^{\mathrm{o}}d^{\mathrm{i}}}{2} \left(1 - \left(\frac{\lambda - 1}{\lambda}\right)^2\right).$$

- For  $\lambda = 2$ , i.e. outer BMD decoding, our results coincide with [Kovalev, 1986], i.e.  $\rho(2) \approx \frac{3d^{\circ}d^{i}}{8}$ .
- In [Schmidt et al., 2006] a BD decoder with parameter  $\lambda = \frac{\ell+1}{\ell}$  for Interleaved Reed–Solomon (IRS) codes<sup>1</sup> is presented, where  $\ell$  is the number of interleaved codes.
- Expressed in terms of  $\ell$  the decoding radius is

$$e < \rho(\ell) \approx \frac{d^{\mathrm{o}}d^{\mathrm{i}}}{2} \left(1 - \left(\frac{1}{(1+\ell)^2}\right)\right).$$

<sup>&</sup>lt;sup>1</sup>IRS codes can be interpreted as punctured RS codes and vice versa [Sidorenko et al., 2008].

# Conclusions/Outlook



- Derived single-trial adaptive algorithm for decoding concatenated codes.
- Provided tight bounds for its decoding radius.
- For outer BMD decoding ( $\lambda = 2$ ), decoding radius coincides with [Kovalev, 1986], i.e.  $e < \rho(2) \approx \frac{3d^od^i}{8}$ .
- For outer BD decoding, the decoding radius quickly approaches  $\frac{d^{\circ}d^{i}}{2}$  for decreasing error/erasure tradeoff parameter  $\lambda$ .
- In special case of outer IRS codes, the radius approaches  $\frac{d^{\circ}d^{i}}{2}$  quadratically with number  $\ell$  of interleaved codes.
- Next step: Error exponent analysis, investigate influence of outer BD decoder's error probability.

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## Upper Bound for the Error Correcting Radius (1)

#### Theorem (Upper Bound)

$$\rho(\lambda) \leq \overline{\rho}(\lambda) := \frac{d^{\mathrm{i}}}{\lambda} \left( d^{\mathrm{o}} - 1 - \frac{1}{2} \left\lfloor \frac{d^{\mathrm{o}} - 1}{\lambda} \right\rfloor \right)$$

Proof (Sketch): Derive a lower bound on

$$\max_{\boldsymbol{h}} \min_{\boldsymbol{\tau}} \left( \frac{1}{2} \sum_{j=1}^{d^{\mathrm{o}}} h_j - \sum_{j=\tau+1}^{\tau+\varepsilon(\tau)} h_j \right),$$

this means to maximize the second sum  $\sum_{j=\tau+1}^{\tau+\varepsilon(\tau)} h_j$ .

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# Upper Bound for the Error Correcting Radius (2)



Consider example on the left,  $\lambda=3/2, \ d^{\rm o}=13, \ \varepsilon(0)=9.$ 

Choose h s. t.  $\sum_{j=\tau+1}^{\tau+\varepsilon(\tau)} h_j$  is constant for all decisive  $\tau$ .

$$h_j = \begin{cases} \frac{\lambda - 1}{\lambda} & j = 1, \dots, \varepsilon(0) \\ 1 & j = \varepsilon(0) + 1, \dots, d^{\mathrm{o}} \end{cases}$$

Then: 
$$\sum_{j=\tau+1}^{\tau+\varepsilon(\tau)} h_j = \varepsilon(0) - \frac{\varepsilon(0)}{\lambda}$$

Inserting proves the Theorem.

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### Tightness of the Bounds



#### Corollary (Conformity of the Bounds)

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 $\lambda = \frac{\ell+1}{\ell}, \ \ell \in \mathbb{N} \setminus \{0\}$ 

and

$$d^{o} = s(\ell+1)^{2} + \ell + 2, \ s \in \mathbb{N},$$

then

$$\underline{\rho}(\lambda) = \rho(\lambda) = \overline{\rho}(\lambda).$$

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